

Limit Cycles II

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MOL 410/510

How to prove a closed orbit exists?

- numerically
- Poincaré-Bendixson Theorem: If
 1. R is a closed, bounded subset of the plane
 2. $\dot{\vec{x}} = \vec{f}(\vec{x})$ is a continuously differentiable vector field on an open set containing R
 3. R does not contain any fixed points
 4. There exists a trajectory C that is “confined” in R

Then either C is a closed orbit or it spirals towards a closed orbit as $t \rightarrow \infty$. Either way, R contains a closed orbit.

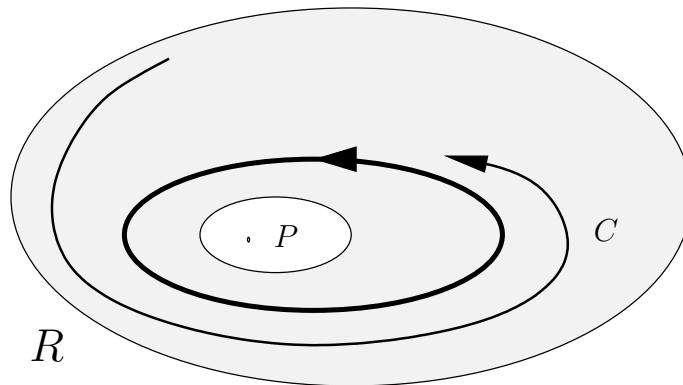


Figure 1: Poincaré-Bendixson Theorem

Example — Glycolytic oscillations

Background

Organisms may obtain energy by breaking down sugar. Glycolysis can proceed in an oscillatory fashion. In a simple model with

x = concentration of ADP (adenosine diphosphate)

y = concentration of F6P (fructose-6-phosphate)

we have

$$\begin{aligned}\dot{x} &= -x + ay + x^2y \\ \dot{y} &= b - ay - x^2y\end{aligned}$$

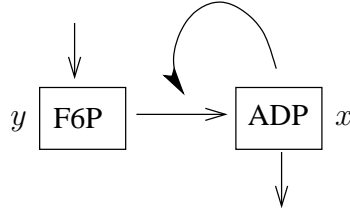


Figure 2: Glycolysis model

Starting from Kinetic Equations

A brief aside on deriving dimensionless equations from kinetic equations - by rescaling chemical concentrations and time by appropriate units, one can generally reduce the number of parameters. In our case, the underlying kinetic equations are

$$\begin{aligned}\frac{d[A]}{dt} &= -\mu[A] + \alpha[F] + \gamma[A]^2[F] \\ \frac{d[F]}{dt} &= \beta - \alpha[F] - \gamma[A]^2[F]\end{aligned}$$

which has four (dimensionful) parameters, α , β , γ , and μ . We'll start by rescaling time. Divide by μ , which is a rate, to give

$$\begin{aligned}\frac{d[A]}{d(\mu t)} &= \frac{d[A]}{dt'} = -[A] + (\alpha/\mu)[F] + (\gamma/\mu)[A]^2[F] \\ \frac{d[F]}{d(\mu t)} &= \frac{d[F]}{dt'} = \beta/\mu - (\alpha/\mu)[F] - (\gamma/\mu)[A]^2[F],\end{aligned}$$

where we have defined $t' = \mu t$. Now, to eliminate the parameter γ/μ in front of the last term in each equation, while continuing to measure $[A]$ and $[F]$ in the same units, we'll rescale the concentrations $[A]$ and $[F]$ as

$$\begin{aligned}[A] &= (\mu/\gamma)^{1/2}x \\ [F] &= (\mu/\gamma)^{1/2}y,\end{aligned}$$

which yields

$$\begin{aligned}(\mu/\gamma)^{1/2} \frac{dx}{dt'} &= -(\mu/\gamma)^{1/2}x + (\alpha/\mu)(\mu/\gamma)^{1/2}y + (\gamma/\mu)(\mu/\gamma)^{3/2}x^2y \\ (\mu/\gamma)^{1/2} \frac{dy}{dt'} &= \beta/\mu - (\alpha/\mu)(\mu/\gamma)^{1/2}y - (\gamma/\mu)(\mu/\gamma)^{3/2}x^2y,\end{aligned}$$

and simplifies to

$$\begin{aligned}\dot{x} &= -x + (\alpha/\mu)y + x^2y \\ \dot{y} &= (\gamma/\mu)^{1/2}(\beta/\mu) - (\alpha/\mu)y - x^2y.\end{aligned}$$

These are our original, dimensionless equations, and now we can see exactly how the two remaining dimensionless constants a and b depend on the underlying rates in the kinetic equations: $a = \alpha/\mu$ and $b = (\gamma/\mu)^{1/2}(\beta/\mu)$.

Intuition

Since rate of F6P→ADP increases with ADP, we can get “overshooting,” i.e. F6P gets depleted, ADP has no source so it also gets depleted, followed by slow recovery of F6P. This is a possible oscillator, but how can we prove a limit cycle?

Find the nullclines

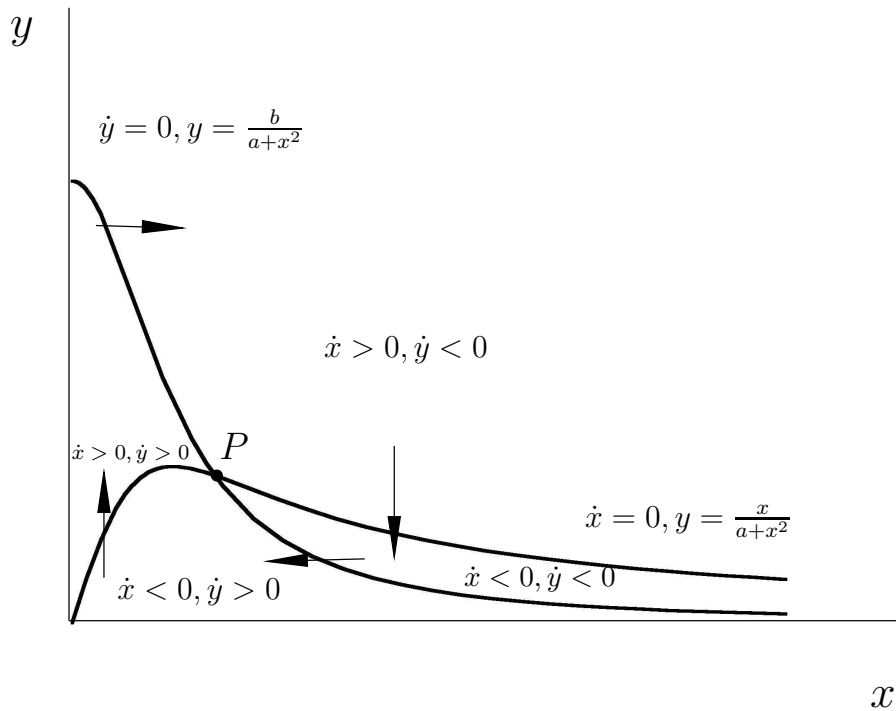


Figure 3: Nullclines sketch

$$\begin{aligned}x\text{-dot} = 0 &\implies -x + ay + x^2y = 0 \\ &\implies y = \frac{x}{a+x^2} \\ y\text{-dot} = 0 &\implies b - ay - x^2y = 0 \\ &\implies y = \frac{b}{a+x^2}\end{aligned}$$

Solve for fixed point: $x = b, y = \frac{b}{a+b^2}$.

Does this prove a limit cycle? *NO!* We could have a stable fixed point at P , or trajectories could spiral out to ∞ . Indeed, at the intersection of the nullclines $\dot{x} = \dot{y} = 0$, so P is a fixed point.

Fixed point

We can't apply Poincaré-Bendixson yet because of the fixed point. We *can* use P-B, though, if the fixed point is a repeller, because then our trapping region is just $R \setminus P$. Analyze stability of fixed point P by linearizing the differential equations around the fixed point:

$$\text{Jacobian } A = \begin{pmatrix} \frac{\partial \dot{x}}{\partial x} & \frac{\partial \dot{x}}{\partial y} \\ \frac{\partial \dot{y}}{\partial x} & \frac{\partial \dot{y}}{\partial y} \end{pmatrix} = \begin{pmatrix} -1 + 2xy & a + x^2 \\ -2xy & -(a + x^2) \end{pmatrix}$$

$$\text{Fixed point } P: x^* = b, y^* = \frac{b}{a + b^2}$$

$$A(P) = \begin{pmatrix} -1 + 2\frac{b^2}{a+b^2} & a + b^2 \\ -\frac{2b^2}{a+b^2} & -(a + b^2) \end{pmatrix}$$

$$\Delta = \det A(P) = a + b^2 > 0$$

$$\tau = \text{tr } A(P) = -1 + 2\frac{b^2}{a+b^2} - (a + b^2) = -\frac{b^4 + (2a-1)b^2 + (a+a^2)}{a+b^2}$$

In general, we can quickly determine the stability of a fixed point if we know Δ and τ , i.e. the determinant and trace of the Jacobian at the fixed point, because the eigenvalues are given by

$$\lambda_J = \frac{1}{2}(\tau \pm \sqrt{\tau^2 - 4\Delta}).$$

(It's worth remembering that for any square matrix $\Delta = \prod_i \lambda_i$ and $\tau = \sum_i \lambda_i$.)

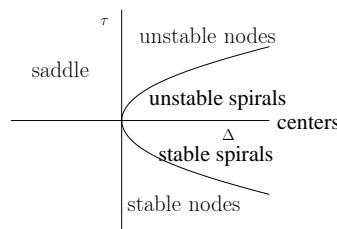


Figure 4: Stability and types of fixed points

The fixed point P is unstable for $\tau > 0$, stable for $\tau < 0$. The dividing line $\tau = 0$ is at

$$b^2 = \frac{1}{2}(1 - 2a \pm \sqrt{1 - 8a})$$

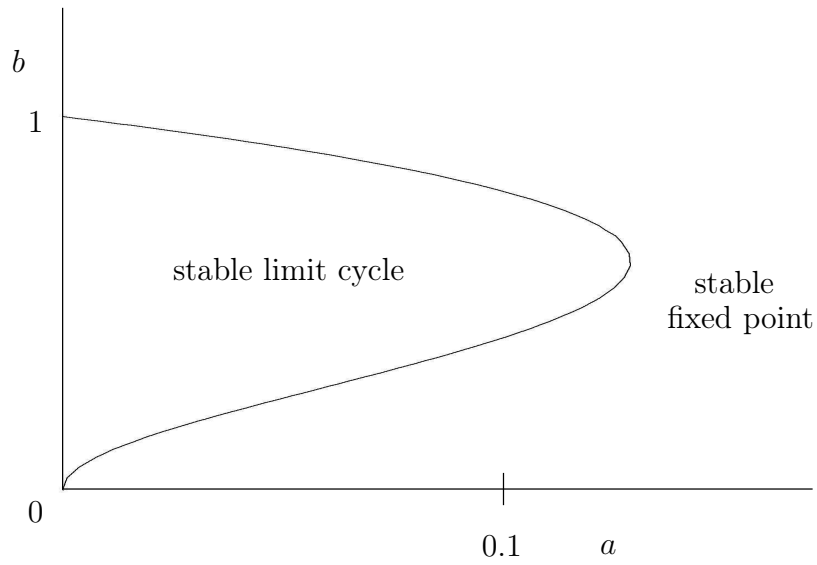


Figure 5: Glycolysis analysis

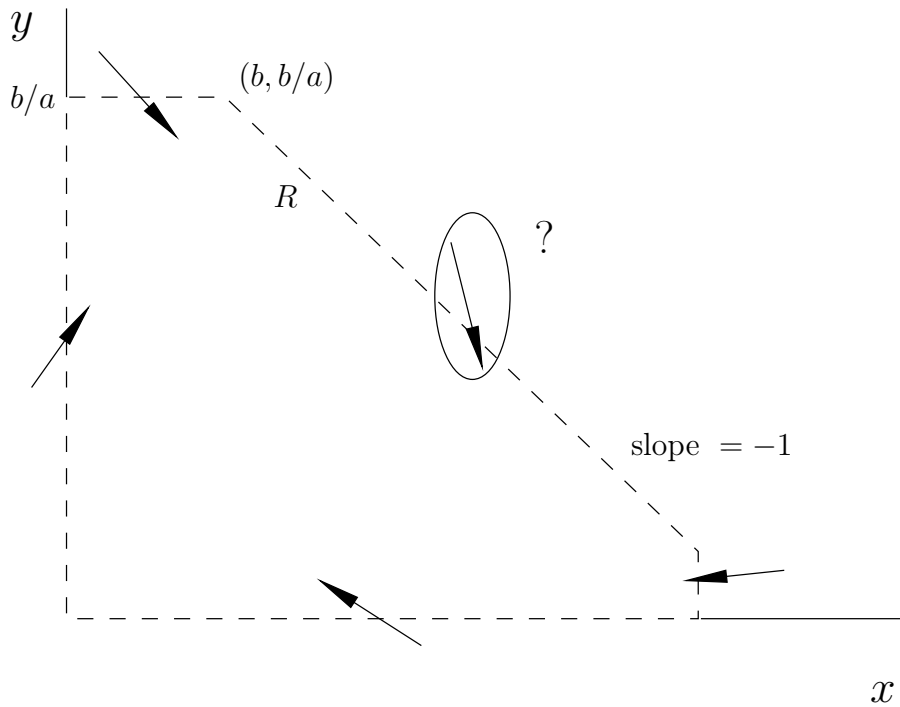


Figure 6: Trapping region

Find a trapping region

Examine Figure 6 (page 6). The vectors for $\dot{x} = 0$ or $\dot{y} = 0$ follow from the last figure. But what about the circled vector?

Circled vector is trapping if $\dot{y} < -\dot{x}$ (i.e. $\dot{x} + \dot{y} < 0$) along the boundary:

$$\dot{x} + \dot{y} = -x + b \implies \dot{x} + \dot{y} < 0 \text{ if } x > b,$$

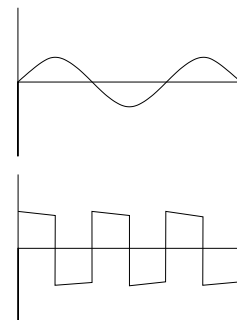
so the dashed lines do define a trapping region.

A model for glycolysis

We can conclude that our glycolytic model functions as in Figure 5 (page 5). Does this make sense? If a is too big, then $\text{F6P} \rightarrow \text{ADP}$ even for low levels of ADP, so there's no chance for a pool of F6P to accumulate. At a fixed a , if b is too small then new F6P will "instantly" turn into ADP and get used up, so the system is locked in a low flux state. If b is too big, ADP will never be low enough, so the system is locked into a high flux state.

How to characterize a limit cycle?

- (nearly) harmonic oscillator vs relaxation oscillator
- period
- amplitude



Example - van der Pol oscillator

$$\ddot{x} + \mu(x^2 - 1)\dot{x} + x = 0$$

Damped harmonic oscillator: ordinary damping for $|x| > 1$, “negative” damping for $|x| < 1$. Large amplitude oscillations will decay, but small amplitude oscillations will get pumped up. Like a parent pushing a child on a swing...

It can be proven that the van der Pol oscillator has a single, stable limit cycle for each $\mu > 0$.

van der Pol as a relaxation oscillator ($\mu \gg 1$)

$$\ddot{x} + \mu(x^2 - 1)\dot{x} = \frac{d}{dt} \left[\dot{x} + \mu \left(\frac{1}{3}x^3 - x \right) \right]$$

$$\text{Let } F(x) = \frac{1}{3}x^3 - x, \omega = \dot{x} + \mu F(x).$$

The van der Pol equation implies

$$\dot{\omega} = -x, \quad \dot{x} = \omega - \mu F(x),$$

and if we let $y = \omega/\mu$,

$$\begin{aligned} \dot{x} &= \mu[y - F(x)] && \leftarrow \text{fast} \\ \dot{y} &= -\frac{1}{\mu}x && \leftarrow \text{slow} \end{aligned}$$

Nullclines

So there are two separated timescales:

$$\begin{aligned} \text{“crawls”} & \quad \Delta t \sim \mu \\ \text{“jumps”} & \quad \Delta t \sim 1/\mu \end{aligned}$$

Period

The period of relaxation oscillator is dominated by crawls. For van der Pol, by symmetry $T \approx 2 \int_{t_A}^{t_B} dt$.

On the slow branches:

$$\frac{dy}{dt} \approx \frac{dy}{dx} \Big|_{\text{Nullcline}} \frac{dx}{dt} = \frac{dF(x)}{dx} \frac{dx}{dt} = (x^2 - 1) \frac{dx}{dt}.$$

But

$$\frac{dy}{dt} = -\frac{1}{\mu}x,$$

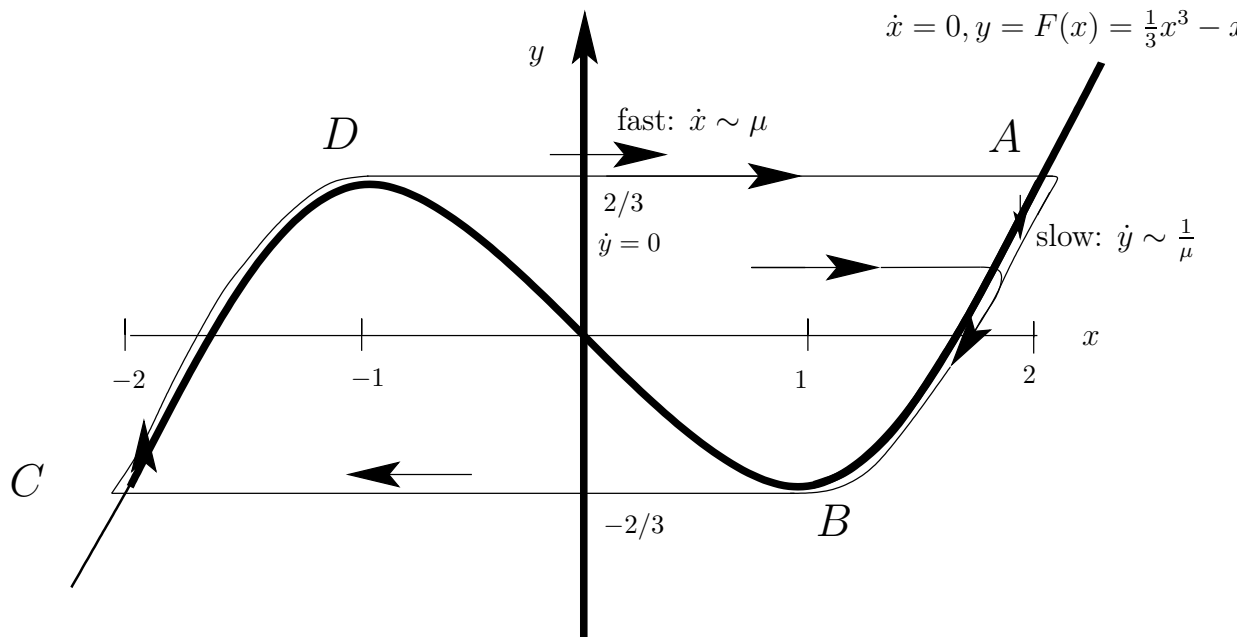


Figure 7: van der Pol nullclines

so

$$-\frac{1}{\mu}x \approx (x^2 - 1)\frac{dx}{dt}$$

and

$$dt \approx -\frac{\mu(x^2 - 1)}{x}dx.$$

Therefore:

$$\begin{aligned} T &= 2 \int_{t_A}^{t_B} dt \approx 2 \int_{x_A}^{x_B} -\frac{\mu(x^2 - 1)}{x} dx \\ &= 2\mu \left[\frac{x^2}{2} - \ln x \right]_1^2 && \text{since } (x_A = 2, x_B = 1) \\ &= \mu(3 - 2 \ln 2) \sim \mu && \checkmark \end{aligned}$$